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(21) International Application Number: PCT/SE99/02493 (22) International Filing Date: 28 December 1999 (28.12.1999) (30) Priority Data: 09/231,886 14 January 1999 (14.01.1999) US (60) Parent Application or Grant TELEFONAKTIEBOLAGET LM ERICSSON (publ) [/]; O. LUNDQVIST, Stellan [/]; O. OHLSSON, Mattias [/]; O. NYGREN, Jörgen [/]; O. KLAS, Norin ; O.		Published
(54) Title: ADAPTIVE JITTER BUFFERING (54) Titre: STOCKAGE ADAPTATIF DE GIGUE EN FILE D'ATTENTE (57) Abstract <p>In a packet communication system, the delay time needed in a jitter buffer is determined, enabling a smooth data feed to an application without excessive delays, by methods and apparatus that vary the size of the jitter buffer based on an estimated variation of packet transmission delay derived from the times of arrival of stored packets. A variance buffer stores variances of the times of arrival of stored packets, and the estimated variation of packet transmission delay is derived from the stored variances. The size of the jitter buffer can be changed preferentially during periods of discontinuous packet transmission.</p> (57) Abrégé <p>Dans un système de communication par paquets, on détermine le délai nécessaire dans une file d'attente pour gigue, ce qui permet d'alimenter une application avec des données de façon coulante et sans délais excessifs, et ce au moyen d'un appareil qui modifie la taille de la file d'attente pour gigue sur la base d'une variation estimée du délai de transmission de paquets, dérivée du temps d'arrivée des paquets stockés. Une file d'attente pour variances stocke les variances du temps d'arrivée des paquets stockés, après quoi la variation estimée du délai de transmission de paquets est dérivée à partir des variances stockées. La taille de la file d'attente pour gigue peut être modifiée, de préférence pendant les périodes de transmission discontinue de paquets.</p>		

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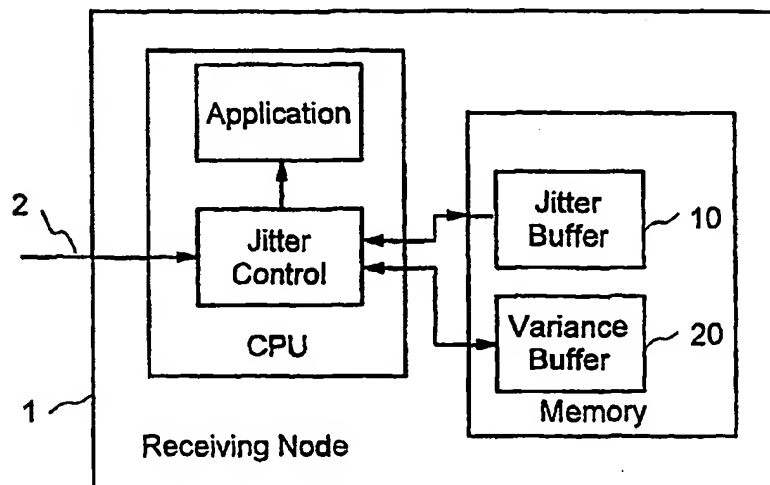
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(54) Title: ADAPTIVE JITTER BUFFERING



(57) Abstract

In a packet communication system, the delay time needed in a jitter buffer is determined, enabling a smooth data feed to an application without excessive delays, by methods and apparatus that vary the size of the jitter buffer based on an estimated variation of packet transmission delay derived from the times of arrival of stored packets. A variance buffer stores variances of the times of arrival of stored packets; and the estimated variation of packet transmission delay is derived from the stored variances. The size of the jitter buffer can be changed preferentially during periods of discontinuous packet transmission.

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ADAPTIVE JITTER BUFFERING

BACKGROUND

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This invention relates to electrical telecommunication and more particularly to packet networks using the Internet Protocol and even more particularly to minimizing delays in packet delivery in such networks.

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Applications sending real-time data streams over unreliable Internet Protocol (IP) networks have a lot of problems to overcome, including long and variable delays and lost and out-of-sequence packets. Today, these problems can be reduced by using techniques such as the Real Time Protocol (RTP) and jitter buffers.

20

The RTP is a real-time transport protocol that provides end-to-end network transport functions suitable for applications transmitting real-time data, such as audio, video, or simulation data, over multicast or unicast network services. The RTP does not address resource reservation and does not guarantee quality-of-service for real-time services. The RTP provides for sequence numbering, which tells the receiving node if the packets are arriving in sequence or at all. The data transport is augmented by a control protocol (RTCP) to allow monitoring of the data delivery in a manner scalable to large multicast networks, and to provide minimal control and identification functionality. The RTP and RTCP are designed to be independent of the underlying transport and network layers. The RTP is specified in H. Schulzrinne et al., Request for Comments 1889 "RTP: A Transport Protocol for Real-Time Applications", <http://194.52.182.96/rfc/rfc1889.html> (Feb. 1, 1996).

30

Jitter buffers are memories in receiving nodes that are used for sorting the packets into the correct sequence, and delaying the packets as needed to compensate for variations in network delay. The RTP specification discusses such interarrival jitter in Section 6.3.1 and Appendix A.8 that provide for forming a 32-bit estimate of the statistical variance of the RTP data packet interarrival time, measured in timestamp units and expressed as an unsigned integer. The interarrival jitter J is defined to be the mean deviation (smoothed absolute value) of the difference D in packet spacing at the receiver compared to the sender for a pair of packets. As shown in the equation below, this is equivalent to the difference in the "relative transit time" for the two packets; the relative transit time is the difference between a packet's RTP timestamp and the receiver's clock at the time of arrival, measured in the same units. If S_i is the RTP

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5 timestamp from packet i, and R_i is the time of arrival in RTP timestamp units for packet i, then for two packets i and j, D may be expressed as:

$$D(i, j) = (R_j - R_i) - (S_j - S_i) = (R_j - S_j) - (R_i - S_i)$$

10 The interarrival jitter is calculated continuously as each data packet i is received from the source, using this difference D for that packet and the previous packet i-1 in order of arrival (not necessarily in sequence), according to the formula:

$$J = J + (|D(i - 1, i)| - J)/16$$

15 This algorithm is the optimal first-order estimator and the gain parameter 1/16 gives a good noise reduction ratio while maintaining a reasonable rate of convergence.

20 The problem today is determining the delay time needed in the jitter buffer to achieve a smooth data feed to the application, without excessive delays. This problem can seriously affect voice communication using the Internet/Intranet as the backbone for transmitting the speech. In addition, the need for smarter use of network bandwidth will become more and more important as the number of users of IP telephony increases.

25 In the communications between a mobile cellular telephone and a radio base station, it is common to employ a technique called discontinuous transmission (DTX) mainly to save battery power in the mobile. Briefly stated, DTX means that a transmitter does not send any data if it does not have any new data to send. When a mobile station detects that the user is not speaking, the mobile station sends only Silence Descriptor (SID) frames that contain background noise. The SID frames are sent periodically, generally about every 480 milliseconds, and between the SID frames the mobile station sends nothing.

30 The idea of using DTX to save bandwidth has been brought up in the IMTC Voice over IP Forum Technical Committee (V61P 1A 1.0), but no implementations have yet been discussed. There are also some special cases that need to be handled when using DTX over an IP network.

SUMMARY

45 Applicants' invention solves the problem of determining the delay time needed in a jitter buffer and achieves the object of obtaining a smooth data feed to an application, without excessive delays. Thus, Applicants' invention improves voice communication using the Internet/Intranet as the backbone for transmitting the speech and uses network bandwidth more intelligently.

5 In one aspect of the invention, there is provided a receiving node in a packet
communication system that includes a jitter buffer that has a variable size, that stores
packets arriving at the receiving node, and that releases stored packets to an
10 application executing in the receiving node, wherein each packet has a respective
5 sequence number, stored packets are released periodically, and each entry in the jitter
buffer has one of a plurality of states; and a processor that varies the size of the jitter
buffer based on an estimated variation of packet transmission delay derived from the
15 times of arrival of stored packets.

The receiving node may further include a variance buffer that stores variances of
10 the times of arrival of stored packets, and the time that the first-arrived packet is
released is based on the time of arrival of the first packet and the initial delay, and the
20 estimated variation of packet transmission delay is derived from the stored variances.

The states of the jitter buffer entries may be free, busy, and used, the free state
25 indicating that no arrived packet is stored at that location in the jitter buffer, the busy
15 state indicating that an arrived packet is stored at that location in the jitter buffer, and
the used state indicating that an arrived packet stored at that location is being released
to the application. Arrived packets may then be stored in respective locations that are
30 marked in the busy state; packets may be released in response to queries by the
application; and when the application queries the jitter buffer for a next packet, that
20 packet's respective location may be changed to the used state and the respective
location of the previously arrived packet may be changed to the free state.

The processor may decrease the size of the jitter buffer while the receiving node
35 is in a discontinuous transmission mode, thereby avoiding discarding arrived packets
that hold speech information. The receiving node may then include a DTX buffer that
40 25 stores selected packets arriving at the receiving node. An arriving packet is selected
based on at least one of whether the arriving packet is first to arrive after a speech
period and holds total noise information and whether the arriving packet contains noise-
update information, arrives after a speech period, and has a respective sequence
45 number that is subsequent to the sequence number of an earlier arriving packet holding
30 speech information. The processor then changes the size of the jitter buffer while
packets are being selected, thereby avoiding discarding packets holding speech
information.

50 In another aspect of the invention, there is provided a method of storing in a
buffer packets arriving at a receiving node in a packet communication system and

5 releasing arrived packets to an application executing in the receiving node. The method includes the steps of determining a time T_r to release a first arrived packet to the application, the time T_r being the first packet's arrival time T_a plus an initial delay, 10 while waiting for the first arrived packet to be released from the buffer, comparing a current time to the time T_r and releasing the first arrived packet when the time T_r has passed, and after the first arrived packet is released, releasing stored packets periodically at first intervals.

15 The comparing may be performed in response to queries from the application that occur periodically at second intervals, stored packets arrived after the first arrived 20 packet may be released in response to queries from the application that occur periodically at the first intervals, and the first interval may be at least as long as the second interval. Also, the first interval may be substantially equal to transmission intervals between arriving packets.

25 In a further aspect of the invention, there is provided a method of adapting a size of a buffer that stores packets arriving at a receiving node in a packet communication system. The method includes the steps of: counting a number of arrived packets 30 having sequence numbers lower than that of an oldest arrived packet stored in the buffer; comparing the number to an accepted loss parameter; if the number is greater than the accepted loss parameter, increasing a change indicator counter and if the 35 number is equal to or less than the accepted loss parameter, decreasing the change indicator counter; increasing the size of the buffer when the change indicator counter reaches an indicator roof parameter if the buffer is not already at its largest permitted size; and decreasing the size of the buffer when the change indicator counter reaches an indicator floor parameter if the buffer is not already at its smallest permitted size.

40 25 The step of determining the size of the buffer may be performed by determining an expected arrival time of a packet in relation to an arrival time of a first packet of a packet sequence; determining an arrival time variance for the packet; determining a measured delay that is a time the packet will be delayed in the buffer; determining a 45 desired delay based on the arrival time variance and the accepted loss parameter; and 30 determining the size of the buffer based on the desired delay and the measured delay.

50 The arrival time variances may be stored in a variance buffer and sorted and normalized. Also, measured delays may be accumulated for packets having arrival time variances stored in the variance buffer, and the desired delay may be determined based on the sorted, normalized arrival time variances and the accepted loss

5 parameter. The size of the buffer is then determined based on the desired delay and an average measured delay derived from the accumulated measured delays.

10 The size of the buffer may be decreased while the receiving node is in a discontinuous transmission mode, thereby avoiding discarding arrived packets that hold
5 speech information. The method may then include the step of storing in a DTX buffer selected packets arriving at the receiving node. An arriving packet is selected based on at least one of whether the arriving packet is first to arrive after a speech period and
15 holds total noise information and whether the arriving packet contains noise-update information, arrives after a speech period, and has a respective sequence number that
10 is subsequent to the sequence number of an earlier arriving packet holding speech information. The size of the buffer is then changed while packets are being selected, thereby avoiding discarding packets holding speech information.

BRIEF DESCRIPTION OF THE DRAWINGS

25 The invention and its objects and advantages will be understood by reading this description in conjunction with the drawings, in which:

FIG. 1 illustrates a packet header format;

FIGS. 2A, 2B illustrate a receiving node having a jitter buffer;

30 FIG. 3 illustrates a method of storing and releasing packets in the jitter buffer;

FIG. 4 illustrates a method of determining when to change the size of a jitter

20 buffer;

FIG. 5 illustrates a method of determining a size change of a jitter buffer;

35 FIGS. 6A, 6B illustrate a buffer for storing packet arrival time variances;

FIG. 7A illustrates measured delays for packets in the jitter buffer;

FIG. 7B illustrates a principle behind the buffer size change determination; and

40 25 FIGS. 8A, 8B illustrate operation of a jitter buffer with discontinuous packet transmission.

DETAILED DESCRIPTION

45 Applicants' invention solves the problem of determining the delay time needed in a jitter buffer to achieve a smooth data feed to an application, without excessive delays.

30 Applicants' solution needs only an initial delay value to be provided, after which it adapts itself to a suitable delay by measuring arrival time variations and a number of packets arriving too late. Applicant's solution is based on an assumption that the
50 transmitter sends the data packets at intervals that are known to the receiver, e.g., regular intervals.

5 In accordance with Applicants' invention, an adaptive jitter buffer stores data packets arriving at a node over the IP network and handles data packets that arrive late or out of sequence. The transmitter sends the data packets over the network using a
10 protocol such as the RTP that provides for a respective sequence number in each packet, which tells the receiving buffer in what sequence the arriving packets should be entered into the buffer.

15 As an example of a useful protocol, the header format of RTP packets is illustrated by FIG. 1, which indicates bit positions and octet numbers across the top. Each header comprises at least twelve of octets organized into the following fixed
20 header fields:

20 version (V): 2 bits
padding (P): 1 bit
extension (X): 1 bit
contributing source (CSRC) count (CC): 4 bits
25 15 marker (M): 1 bit
payload type (PT): 7 bits
sequence number: 16 bits
30 timestamp: 32 bits
synchronization source (SSRC): 32 bits
20 CSRC list: 0 to 15 items, 32 bits each

35 The first twelve octets are present in every RTP packet, while the list of CSRC identifiers is present only when inserted by a RTP mixer. The details of the fixed header fields are described in Section 5.1 of the RTP specification. It is sufficient to note here that the PT field identifies the format of the RTP payload and determines its
40 25 interpretation by the application that is to use the payload. A profile specifies a default static mapping of payload type codes to payload formats. Additional payload type codes may be defined dynamically. An RTP sender emits a single RTP payload type at any given time.

45 The sequence number increments by one for each RTP data packet sent, and
30 may be used by the receiver to detect packet loss and to restore packet sequence. The initial value of the sequence number is random (unpredictable) to make
50 known-plaintext attacks on encryption more difficult, even if the source itself does not encrypt, because the packets may flow through a translator that does. It will be

5 appreciated, therefore, that it is not necessary for the transmitter to use the RTP but only to provide suitable sequence numbers in the packets.

10 In accordance with Applicants' invention, the receiving node determines times to release arrived packets from an adaptive jitter buffer to an application. The arrangement of a receiving node 1 is depicted highly schematically in FIG. 2A and the arrangement of the jitter buffer 10 in the receiving node 1 is depicted in more detail in FIG. 2B. The node 1 receives a stream or sequence 2 of arriving packets that are
15 provided to a processor CPU in the receiving node. As illustrated in FIG. 2A, the processor executes the instructions that make up the application to which the packets are directed as well as the instructions that make up the methods of controlling the jitter
20 buffer 10 and, if provided, a variance buffer 20 that are described in more detail below. The buffers 10, 20 reside in a memory provided in the receiving node 1.

FIG. 2B shows a sequence of incoming data packets 5, 6, 7, . . . that are stored in respective locations in the jitter buffer 10 as indicated by the arrow A. Already
25 arrived packets are released from the buffer 10 to the application as indicated by the arrow B. FIG. 2B depicts a situation in which already arrived packets 3, 4 have already been stored in locations in the buffer 10. The locations in the buffer 10 are identified as either free, used, or busy for reasons that are explained below.

FIG. 3 illustrates the process of storing incoming packets and releasing arrived
20 packets to an application. One important aspect of this method is the calculation of a time T_r to release the first arrived packet to the application (step 302). In essence, this time is the first packet's arrival time T_a plus a specified initial delay that is an initial
35 estimate of a desired delay T_d , which is determined as described below.

While the application waits for data to be released from the jitter buffer 10, the
40 application may query the buffer periodically, at short intervals (step 304). As long as the application is not given a data packet by the jitter buffer, the application does not do anything. Each time the application queries the buffer for the first data packet, the buffer compares the current time t to the release time T_r of the first packet (step 306).
45 It will be appreciated that further packets, i.e., packets arriving after the first arrived packet, can arrive during steps 304, 306 before the first packet has been released.
30 After the release time has passed, the buffer gives the first data packet to the application the next time the application sends a short-interval or "fast" query to the jitter buffer 10 (step 308), or perhaps more precisely the processor in the receiving
50 node that controls the jitter buffer 10.

5 After the first packet is given to the application, it is preferable that no more time
comparisons are done when releasing packets. Incoming packets are stored in the
jitter buffer (step 310) as described below, and packets are given to the application
10 whenever it queries for them (steps 312, 314). These queries for more data can arrive
5 at the jitter buffer 10 with intervals between them that are substantially the same as or
longer than the intervals between the "fast" queries (i.e., these queries are "slow"
15 compared to the queries for the first arrived packet). The time intervals between the
slow queries need not be less than substantially the transmit intervals between the
packets, which as noted above are known to the receiver. In a simple communication
20 system, the packets are transmitted at regular intervals, i.e., the transmit intervals are
substantially equal to each other. In fact, the time intervals between the slow queries
are preferably substantially the same as the packet transmission intervals.

25 It will be appreciated that the fast and slow queries need not arise from the
application, but more generally can be any signals, e.g., from a timer or timers, that can
15 cause the first arrived packet and/or subsequently arrived packets to be released to the
application.

Referring again to FIG. 2B, each jitter buffer entry can be in one of three
30 different states: free, busy, or used. The free state means that no arrived packet is
stored at that location in the buffer; the busy state means that an arrived packet is
20 stored at that location; and the used state means that the arrived packet stored at that
location is being released to or accessed by the application. Packets are released from
35 the jitter buffer 10 in accordance with the value of a read pointer that indicates which
buffer location to access as each query is received from the application. It will be
understood that the read pointer is in essence nothing more than a recirculating
40 25 counter, with each count value corresponding to a respective location in the jitter buffer.

As packets are released from the jitter buffer to the application, the states of the
entries change in the following way. The first packet actually arrived is stored in a
45 location that is marked in the busy state, and the read pointer is initialized to that
location. After the first arrived packet has been released to the application as
30 described above, that location is changed to the used state. It is generally
advantageous for the packet currently being accessed by the application (i.e., the
50 buffer entry in the used state) to be treated as the first packet in the buffer 10. When it
is time for the application to get the next packet, the entry currently in the used state is
changed to the free state and the next entry in the buffer (as indicated by the read

pointer) is transformed from the busy state to the used state. If the next entry in the buffer is in the free state, no packet is given to the application (since there is not an arrived packet stored at that location), and the read pointer indicating which buffer location to read the next time the application queries the buffer for a packet is advanced. If the sequence number of an incoming packet is lower than the sequence number of a used-state packet, the incoming packet is regarded as arriving too late and is discarded.

Four parameters may be used advantageously for configuring Applicants' method of adapting the behavior of the jitter buffer to changing communication conditions: A Sampling Interval is a number of data packets to measure over before a buffer size change calculation is performed. An Acceptable Loss is a number of data packets the loss of which due to delay can be accepted during one Sampling Interval before changing the size of the buffer. Indicator Roof and Indicator Floor parameters are used for controlling the sensitivity of the method. These and other parameters employed in Applicants' methods can generally be changed as desired at any time.

These parameters and a Change Indicator counter are used in Applicants' method of determining when to change the buffer size that is illustrated by the flow chart of FIG. 4, which begins with setting the parameters and initializing the Change Indicator counter to zero (step 402). This method can be executed from time to time at the prompting of the application receiving the packets, but it is currently believed to be preferable for the method to run continuously as packets are received.

The jitter buffer 10 stores incoming packets in respective memory locations (step 404), and checks whether the buffer has received the number of packets specified by the Sampling Interval parameter (step 406). When the number of received packets is greater than the Sampling Interval parameter, the number of packets arriving too late, i.e., the number of arriving packets having sequence numbers lower than that of the packet being accessed by the application (i.e., the buffer entry in the used state), is read from a Lost Packets counter (step 408). The "Lost Packets" count includes only packets that are delayed, not packets that are lost. The Lost Packets counter is updated as each packet is received after being initialized to zero at the start of a sampling interval corresponding to the Sampling Interval parameter.

The Lost Packets count for the sampling interval is compared to the Accepted Loss parameter (step 410). If the Lost Packets count is greater than the Accepted Loss parameter, the Change Indicator counter is increased by one (step 412). If the Lost

5 Packets count is equal to or less than the Accepted Loss parameter, the Change
Indicator counter is decreased by one (step 414). It can be advantageous in some
circumstances for the Change Indicator counter not to be decreased when the Lost
10 Packets count is equal to the Accepted Loss parameter. Such circumstances include
5 for example when the application requires more caution for decreasing the jitter buffer
size. Packets are discarded when the size of the jitter buffer is decreased, so more
caution is usually appropriate to avoid excessively discarding packets when there are
15 rapid up/down changes in the network transmission delay. If this is done, the Accepted
Loss parameter used in the method depicted in FIG. 4 must not be zero.

10 When the Change Indicator counter reaches the Indicator Roof parameter (step
416), it is time to increase the size of the jitter buffer 10, provided the buffer is not
already at its largest permitted size (step 418). When the Change Indicator counter
reaches the Indicator Floor parameter (step 420), it is time to decrease the size of the
20 buffer (step 422), provided the buffer is not already at its smallest permitted size. It is
25 currently believed that the largest buffer size, which corresponds to the longest delay in
the jitter buffer, is dependent on the application. In addition, it can be noted that the
longest delay in the jitter buffer is the same as the longest desired delay T_d if the
Accepted Loss parameter is zero. For example, two-way voice or video communication
30 could find a one-second delay unacceptable but such a delay and even longer delays
could be acceptable for data file transfers and one-way video communication. It is
20 currently believed that the smallest buffer size would typically be one packet, i.e., the
shortest delay T_d would typically be the packet transmission interval. It is conceivable
35 that the smallest buffer size could be zero packets, i.e., packets could be released
immediately upon arrival ($T_d = 0$), but that would require a communication network
25 having little if any variance in transmission delay.

40 Once it is determined that the size of the jitter buffer 10 should be changed by
the method depicted in FIG. 4, the new size of the buffer (step 418 or step 422) can be
determined by the method illustrated by FIG. 5, which begins as the method depicted in
45 FIG. 4 with the jitter buffer 10 storing incoming packets in respective memory locations
30 (step 502). Here, it is not necessary to check whether the buffer has received the
number of packets specified by the Sampling Interval parameter, although this could be
done if desired.

50 During the sampling interval, the arrival time of each packet is compared to the
arrival time of the first packet of this packet sequence. By adding the product of the

5 packet transmission interval and the difference between the sequence numbers of
successive packets to the arrival time of the first packet, the expected arrival time of a
particular packet in relation to the arrival time of the first packet can be determined
10 (step 504). This expected arrival time Ta_n of the packet having sequence number n is
5 given by the following expression:

$$Ta_n = ti \cdot (N_n - N_1) + Ta_1$$

15 where Ta_1 is the arrival time of the first packet, ti is the packet transmission interval, N_n
is the sequence number of the currently arriving packet, and N_1 is the sequence
number of the first packet. Instead of using the arrival time of the first packet in the
10 sequence, the method can use the arrival time of the first packet in the current
sampling interval. Also as part of step 504, measured delays are accumulated as
20 explained in more detail below.

An arrival time variance v for packet n is determined according to the following
expression when the packet n arrives:

25 15
$$v = T_{actual_n} - Ta_n$$

where T_{actual_n} is the actual arrival time the packet arrives. In accordance with one
aspect of the invention, this variance may be stored in the variance buffer 20 (step
30 506). The buffer 20 for storing the variances is preferably separate from the jitter buffer
10 and has a size corresponding to the same length of the sampling interval, so that
20 variances are stored one by one until the buffer 20 is full (step 508). As depicted by
FIG. 6A, the first entry in the buffer 20 represents the first packet of this sampling
35 interval, and the last entry represents the last packet of this sampling interval. The
variance entries in the buffer 20 are sorted and normalized (step 510) such that the
smallest value is zero as depicted in FIG. 6B.

40 25 It will be appreciated that in general it is not necessary to use a variance buffer
20 and that the desired delay, i.e., the size of the jitter buffer, can be determined as
each packet arrives from each packet's respective variance v . Thus, the processes of
steps 506, 508, 510 may be considered, in a way, as operating on a single variance,
45 i.e., that of one of the arrived packets.

30 Based on the contents of the buffer 20 or on an individual variance as just
described, the desired delay Td can be determined (step 512). The example depicted
in FIG. 6B shows that the variance in arrival times is seventeen time units. This means
50 that if the Accepted Loss parameter is set to zero (meaning no packets can be lost),
then the desired delay Td in the jitter buffer 10 during this sampling interval is

seventeen time units. If the Accepted Loss parameter is set to one (meaning one packet can be lost), then the desired delay T_d in the jitter buffer during this sampling interval is thirteen time units. The desired delay T_d is given in general by the following expression:

$$T_d = \text{buffer}(\text{Sampling Interval} - \text{Accepted Loss})$$

if the buffer 20 uses a 1-based indexing mechanism in which the first entry in the buffer is indexed as one, the second entry is indexed as two, etc.

During the sampling interval an accumulated measured delay can be maintained as noted above in connection with step 504. The measured delay is the time the current arriving packet will be delayed in the buffer, as illustrated by FIG. 7A. The measured delays for the packets in the sampling interval can be accumulated as the packets arrive for deriving an average measured delay M_d that is used as described below.

In accordance with Applicants' invention, the desired delay T_d and the measured delay M_d are used for determining the size of any necessary jitter buffer size change (step 514). FIG. 7B graphically describes how the current size of the jitter buffer 10 can be changed by $(T_d/2 - M_d)$ time units without causing arriving packets (T_a) to be considered late.

Packet arrival time variances are represented in FIG. 7B on the horizontal axis. T_a is the time variance in when the application requests new data packets. There will be no or negligible variance in T_a when the application requests packets at regular intervals. The lines D_l and D_u represent the lower and upper limits of the range of variances in packet arrival time for packets in the sampling interval, and the short vertical lines between D_l and D_u represent variances for individual packets. It will be seen that D_u is the variance for the packet selected as the desired delay T_d in the preceding expression. If the range D_l - D_u includes all variances during a sampling interval, then T_d is that for an Accepted Loss value of zero. M_d is the average measured delay, that can be obtained by accumulating the measured delays for packets that actually arrived during this sampling interval, i.e., packets arrived both on time (in the range D_l - D_u) and too late, and dividing by that number of packets.

The purpose of step 514 is to move D_l as close to T_a as possible, i.e., to minimize the measured delay in the jitter buffer without losing packets, according to the following expression:

$$\text{Delay Modification} = T_d/2 - M_d$$

5 The Delay Modification value tells the number of time units that the size of the jitter
buffer should be increased or decreased. This value is rounded up to the closest value
10 that is a multiple of the packet transmission interval, and is then divided by the
transmission interval to find the number of packets more or fewer needed in the jitter
5 buffer.

As indicated by step 516, the jitter buffer size is increased by denying the
15 application newly arriving packets according to the number determined in step 514 and
is decreased by discarding a number of packets according to the number determined in
step 514. It will be understood that steps 510 through 516 correspond to steps 418 and
10 422. In this way, the size of the jitter buffer is adapted to the communication conditions
existing during the sampling interval.

Applicants' method of adapting the jitter buffer size may be implemented
20 advantageously in combination with DTX, which as explained above means that the
transmitter does not send any packets when it does not have any new data to send. If
25 15 this method is used, there will be periods of time when the jitter buffer does not receive
any new data and it is therefore possible to decrease the buffer size without discarding
packets.

30 Another advantage to DTX with an adaptive jitter buffer is provided if the packets
arise from a speech application, such as voice over an IP network. The adaptive jitter
20 buffer can change its size from time to time, and when the buffer size decreases, some
speech frames will be discarded. This can disturb the speech vocoder, distorting the
35 speech. Nevertheless, discarding or losing packets during periods of DTX, e.g.,
silence, avoids the disturbance. As noted above, when a user is not speaking, a
transmitter periodically sends only SID frames that contain background noise. In
40 25 general, using DTX with an adaptive jitter buffer for a speech application requires
storing the SID frames in a separate location in the memory of the receiving node 1, not
in the jitter buffer 10.

45 The following describes an implementation of DTX with an adaptive jitter buffer
in a communication system in accordance with the Global System for Mobile
30 communication (GSM) standard. Such communication systems are well known in the
art so they need not be described in detail here. It will be appreciated that DTX may be
50 employed when the packets hold information other than speech and noise information,
which thus will be understood to mean more generally any first and second types of
information used in the communication system employing DTX.

5 In DTX in a GSM system, the transmitter such as a mobile station generates two types of SID frames or packets and sends them to the radio base station (RBS), which may be a receiving node 1 as described above or which may simply forward the packets to a receiving node 1. One type of SID packet contains the total noise
10 information and the other type of SID packet contains only an update of the noise. Generally, a total-noise SID packet is sent first during a silence period, and after that, noise-update SID packets are sent except in a situation explained in more detail below.

15 The RBS may re-format packets received from a mobile station as RTP packets or the mobile station may produce such packets itself, but in any event, the payload of each RTP packet holding speech or SID data, includes space for two flags: a SID flag that indicates whether the payload is holding speech or SID data, and a TAF flag that identifies the packet as either a total-noise SID packet or a noise-update SID packet. Thus, a node can detect the difference between a total-noise SID packet and a noise-update SID packet by examining the flags, or information elements, included in the
20 packet.
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The RBS forwards toward the IP network the SID packets received from the mobile station, indicating by the two flags whether the payload is SID data and, if it is, whether the SID data is an update or total noise information. Because the total-noise SID is so important and because speech data is sent as user datagram protocol (UDP) packets, the risk of losing the SID can be decreased by sending that packet more than once, either several times all together or for example when it normally occurs and when sending the next noise-update SID packet. The UDP is an IP-standard protocol that enables an application program on a first processor to send datagrams (packets) to an application program on a second processor using the IP to deliver the packets.

30 25 The RBS or other receiving node 1 detects whether a payload is holding speech or SID data, and if the packet is a SID packet, the packet is saved in an area of the receiving node's memory that is different from the jitter buffer 10 as noted above. Also as noted above, usually the first SID packet in a period of silence is very important since it holds the total information of the background noise. Without this information, a
35 vocoder in the receiving node would not be able to reconstruct the noise.
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In current GSM systems, a transmitter like a mobile station needs a period of at least about twenty-four speech frames or packets to be able to prepare a SID packet holding the total noise information. Thus, if the transmitter, during a silence period, detects a short speech burst (e.g., a burst shorter than twenty-four speech packets),
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5 the transmitter will send the last noise-update SID and not the total-noise SID after the short speech burst. This is sometimes called a "hangover" case in the DTX standards, and is a case in which the receiving node should not move into a DTX mode, i.e.,
10 should not direct arriving (SID) packets to memory locations other than the jitter buffer.
5 (See FIG. 8B.) Accordingly, there are two cases when the receiving node 1 should move into a DTX mode, i.e., should direct arriving (SID) packets to memory locations other than the jitter buffer. (See FIG. 8A.)

15 In the first case, the receiving node should move into DTX mode when the first arriving SID packet after a speech period holds the total noise information. In the
10 second case, the receiving node should move into DTX mode when a noise-update SID packet arrives after a speech period and its sequence number is the next following or subsequent to the sequence number of a (earlier) speech frame. These two cases
20 are illustrated by FIG. 8A, which depicts the jitter buffer 10 and three types of packets: DTX (SID) packets D, speech packets S, and too-late, lost or not received packets X.
25 15 From FIG. 8A, it can be seen that the packet D that arrived after the sequence of seven speech packets should be a noise-update SID packet because speech packets do not occur between a total-noise SID and a noise-update SID except in the "hangover" case. Having moved into DTX mode, the SID packet arrived after the last speech packet is
30 released to the application in due course. In a GSM system, the application will only
20 send one particular SID packet to a receiving node like a mobile telephone once. The receiving node, when in DTX mode, moves out of DTX mode when a packet holding
35 speech information arrives.

In cases other than the two depicted by FIG. 8A, packets should not be released
40 25 to the application, i.e., when the node is receiving a noise-update SID and the last packet was lost. This results in a situation similar to the situation when speech packets are lost in an IP network and is illustrated by FIG. 8B, from which it can be seen that the packet X that arrived before the packet D might have been a total-noise SID, making the packet D a noise-update SID. If such a case, i.e., when a total-noise SID
45 has been lost, one should not have the receiving node move into the DTX mode
30 because the received information will be recovered poorly.

Regardless of whether the receiving node moves into DTX mode or not, the jitter
50 buffer should not count lost packets during the time SID packets are received. In other words, it is currently believed that the methods illustrated by FIGS. 4, 5 should not be implemented while SID packets are arriving, except to the extent that the size of the

5 jitter buffer advantageously can be changed based on previously arrived non-SID packets during DTX periods.

10 Assuming packets are arriving at the RBS for transmission to a mobile station, the first SID packet at the start of a silence period is usually sent to the mobile station in
5 a traffic channel established between the RBS and mobile station. All other SID frames during that silence period are usually sent in a control channel, in particular the slow associated control channel (SACCH). If the first SID frame is a total-noise SID frame, it
15 should only be sent once to the mobile station, but if the SID frame that was last sent was a total-noise SID frame and if a noise-update SID frame has not yet arrived and it
10 is time to send a new SID frame to the mobile station in the SACCH, then there might be a problem. Accordingly, at this time, a noise-update SID frame holding information
20 indicating no change in the noise should be sent in accordance with one aspect of Applicants' invention. Such a SID may be called a delta zero SID packet or frame, and the frame including a delta zero SID could be hard coded or generated on the fly (in
25 15 real time) at the time when it is needed.

It will be appreciated by those of ordinary skill in the art that this invention can be embodied in other specific forms without departing from its essential character. The
30 embodiments described above should therefore be considered in all respects to be illustrative and not restrictive. The scope of Applicants' invention is determined by the
20 following claims, and all modifications that fall within that scope are intended to be included therein.

Claims

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WHAT IS CLAIMED IS:

1. A receiving node in a packet communication system, comprising:
a jitter buffer that has a variable size, that stores packets arriving at the receiving
node, and that releases stored packets to an application executing in the receiving
node, wherein each packet has a respective sequence number, stored packets are
released periodically, and each entry in the jitter buffer has one of a plurality of states;
and

a processor that varies the size of the jitter buffer based on an estimated
variation of packet transmission delay derived from the times of arrival of stored
packets.

2. The receiving node of claim 1, further comprising a variance buffer that
stores variances of the times of arrival of stored packets, and wherein a time that a first
arrived packet is released is based on a time of arrival of the first packet and an initial
delay, and the estimated variation of packet transmission delay is derived from the
stored variances.

3. The receiving node of claim 1, wherein the states of the jitter buffer
entries are free, busy, and used, the free state indicates that no arrived packet is stored
at that location in the jitter buffer, the busy state indicates that an arrived packet is
stored at that location in the jitter buffer, and the used state indicates that an arrived
packet stored at that location is being released to the application.

4. The receiving node of claim 3, wherein arrived packets are stored in
respective locations that are marked in the busy state; packets are released in
response to queries by the application; and when the application queries the jitter buffer
for a next packet, that packet's respective location is changed to the used state and the
respective location of the previously arrived packet is changed to the free state.

5. The receiving node of claim 1, wherein the processor decreases the size
of the jitter buffer while the receiving node is in a discontinuous transmission mode,
thereby avoiding discarding arrived packets that hold speech information.

6. The receiving node of claim 5, further comprising a DTX buffer that stores
selected packets arriving at the receiving node; wherein an arriving packet is selected
based on at least one of whether the arriving packet is first to arrive after a speech
period and holds total noise information and whether the arriving packet contains noise-
update information, arrives after a speech period, and has a respective sequence
number that is subsequent to the sequence number of an earlier arriving packet holding

5 speech information; and the processor decreases the size of the jitter buffer while packets are being selected, thereby avoiding discarding packets holding speech information.

10 7. A method of storing in a buffer packets arriving at a receiving node in a packet communication system and releasing arrived packets to an application
5 executing in the receiving node, comprising the steps of:

15 determining a time T_r to release a first arrived packet to the application, wherein the time T_r is the first packet's arrival time T_a plus an initial delay;

while waiting for the first arrived packet to be released from the buffer,

10 comparing a current time to the time T_r and releasing the first arrived packet when the time T_r has passed; and

20 after the first arrived packet is released, releasing stored packets periodically at first intervals.

25 8. The method of claim 7, wherein the comparing is performed in response to queries from the application that occur periodically at second intervals, stored
15 packets arrived after the first arrived packet are released in response to queries from the application that occur periodically at the first intervals, and the first interval is at least as long as the second interval.

30 9. The method of claim 7, wherein the first interval is substantially equal to
20 transmission intervals between arriving packets.

35 10. A method of adapting a size of a buffer that stores packets arriving at a receiving node in a packet communication system, comprising the steps of:

counting a number of arrived packets having sequence numbers lower than that of an oldest arrived packet stored in the buffer;

40 25 comparing the number to an accepted loss parameter;

if the number is greater than the accepted loss parameter, increasing a change indicator counter and if the number is equal to or less than the accepted loss parameter, decreasing the change indicator counter;

45 increasing the size of the buffer when the change indicator counter reaches an indicator roof parameter if the buffer is not already at its largest permitted size; and

30 decreasing the size of the buffer when the change indicator counter reaches an indicator floor parameter if the buffer is not already at its smallest permitted size.

50 11. The method of claim 10, wherein the number is compared when the buffer has stored a number of packets specified by a sampling interval parameter.

5 12. The method of claim 10, further comprising the step of determining the size of the buffer by performing the steps of:

 determining an expected arrival time of a packet in relation to an arrival time of a first packet of a packet sequence;

10 5 determining an arrival time variance for the packet;

 determining a measured delay that is a time the packet will be delayed in the buffer;

15 determining a desired delay based on the arrival time variance and the accepted loss parameter; and

20 10 determining the size of the buffer based on the desired delay and the measured delay.

 13. The method of claim 12, wherein arrival time variances are stored in a variance buffer, stored arrival time variances are sorted and normalized, measured delays are accumulated for packets having arrival time variances stored in the variance
25 15 buffer, the desired delay is determined based on the sorted, normalized arrival time variances and the accepted loss parameter, and the size of the buffer is determined based on the desired delay and an average measured delay derived from the accumulated measured delays.

30 14. The method of claim 10, wherein the size of the buffer is decreased while the receiving node is in a discontinuous transmission mode, thereby avoiding discarding arrived packets that hold speech information.

35 15. The method of claim 14, further comprising the step of storing in a DTX buffer selected packets arriving at the receiving node; wherein an arriving packet is selected based on at least one of whether the arriving packet is first to arrive after a
40 25 speech period and holds total noise information and whether the arriving packet contains noise-update information, arrives after a speech period, and has a respective sequence number that is subsequent to the sequence number of an earlier arriving packet holding speech information; and the size of the buffer is decreased while
45 packets are being selected, thereby avoiding discarding packets holding speech
30 information.

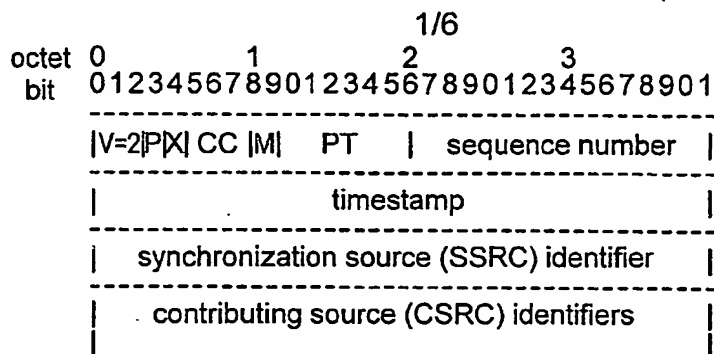


FIG. 1

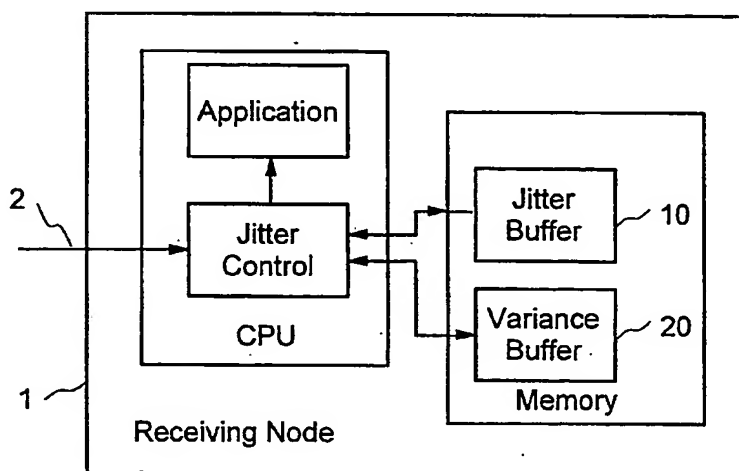


FIG. 2A

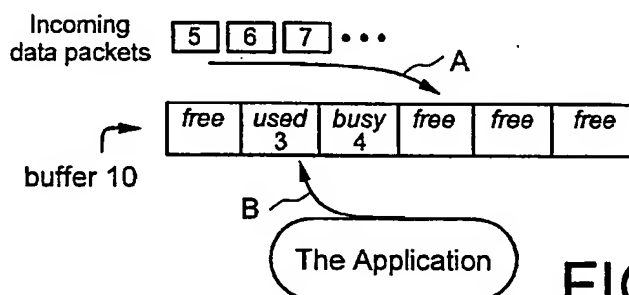


FIG. 2B

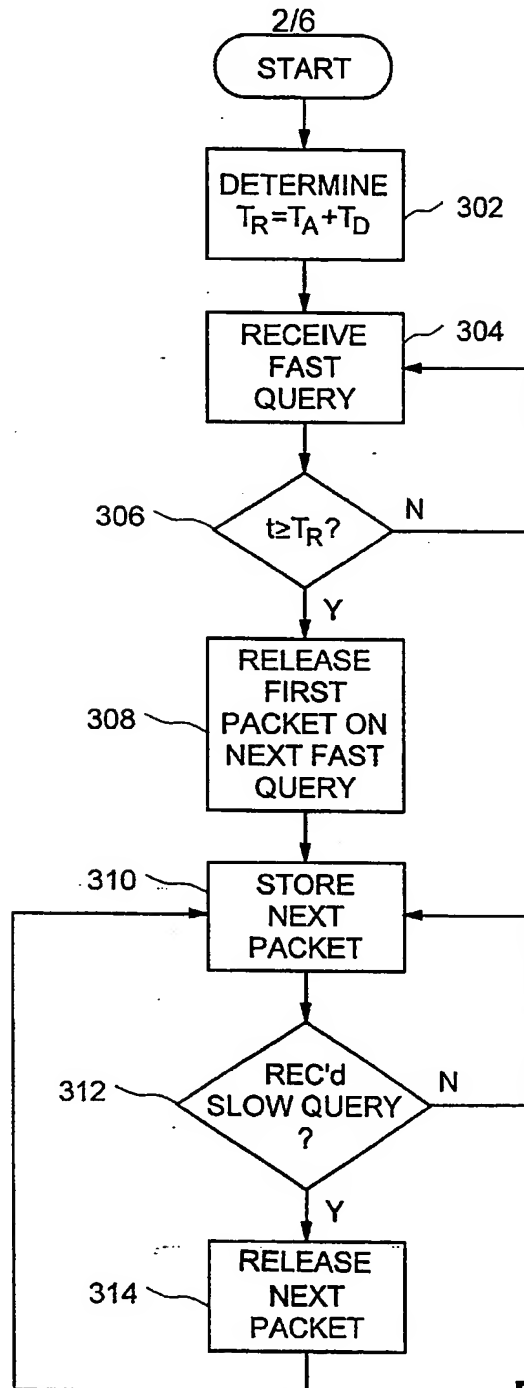


FIG. 3

FIG. 4

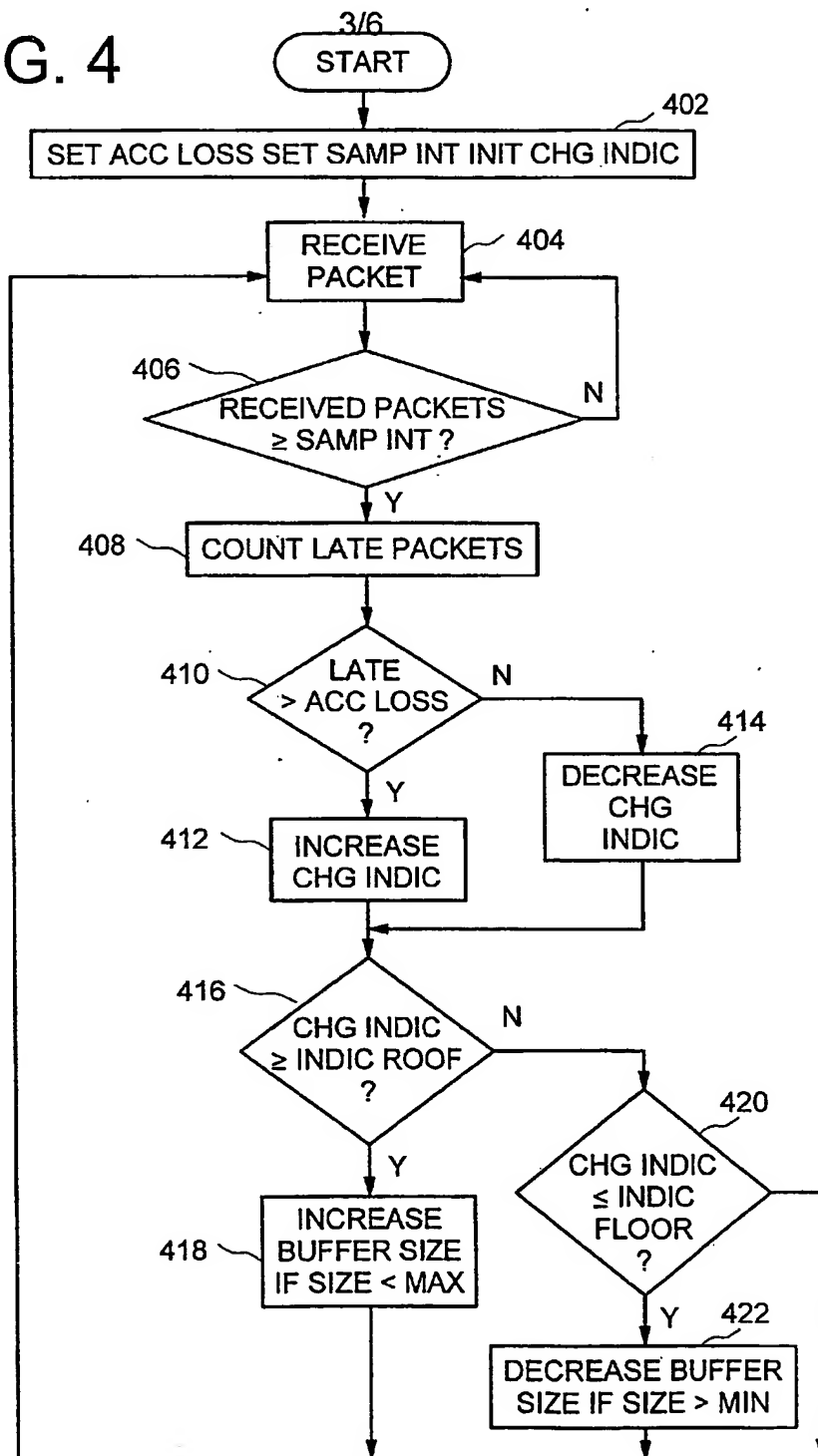
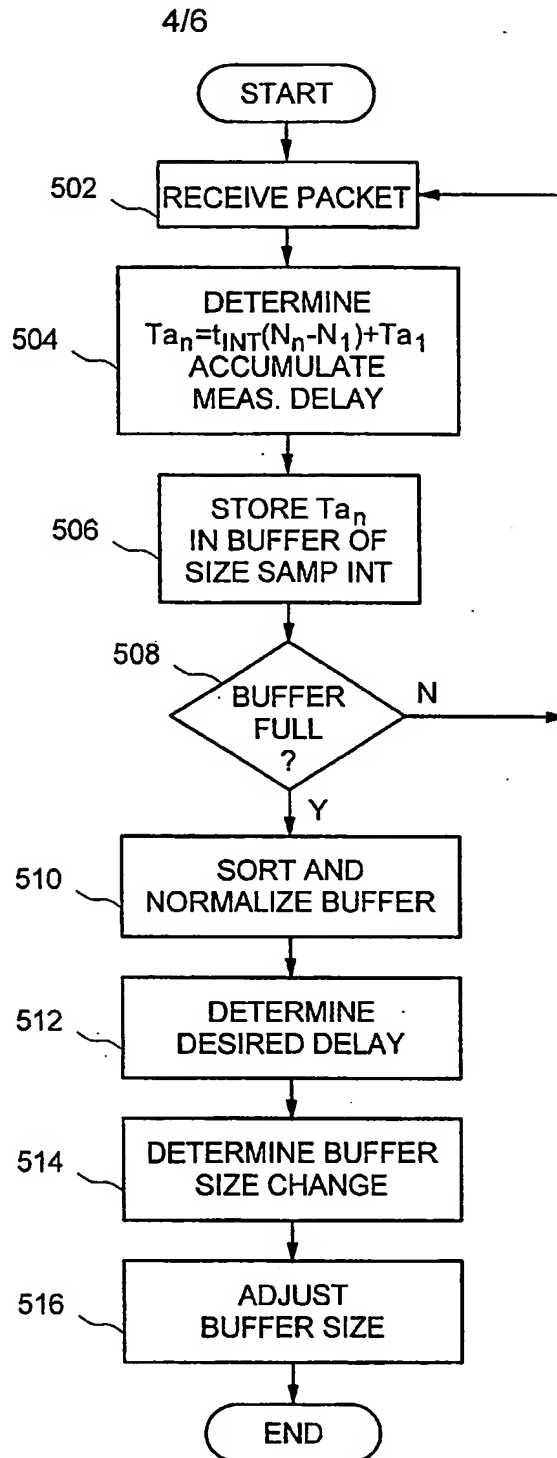


FIG. 5



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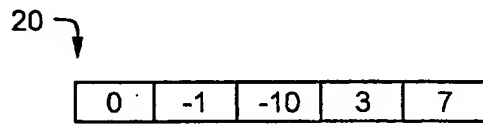


FIG. 6A

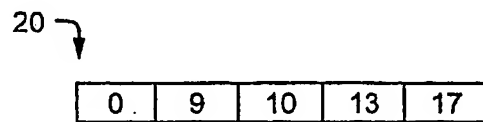


FIG. 6B

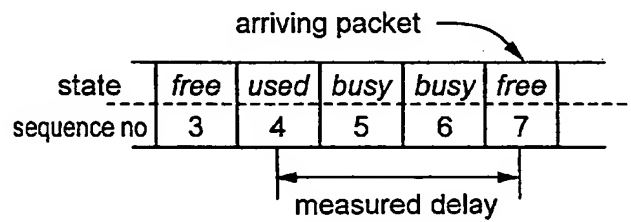


FIG. 7A

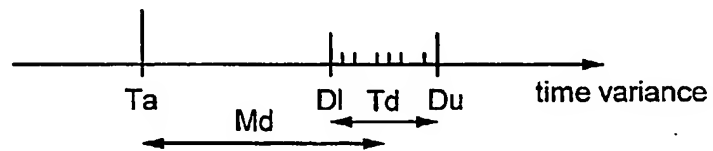


FIG. 7B

buffer 10



D	X	X	X	X	S	S	S	S	S	S	S	D	X	X	X
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

FIG. 8A

buffer 10



D	X	X	X	X	S	S	S	S	S	S	X	D	X	X	X
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

FIG. 8B

INTERNATIONAL SEARCH REPORT

International Application No
PCT/SE 99/02493

A. CLASSIFICATION OF SUBJECT MATTER
IPC 7 H04L12/64

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)
IPC 7 H04L

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practical, search terms used)

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category *	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
Y	WO 96 15598 A (VOCALTEC INC) 23 May 1996 (1996-05-23) page 4, line 18 - line 25 page 7, line 7 - line 15 page 11, line 1 - line 29 page 13, line 7 - line 25	1
A	claim 1	2-15
Y	US 5 604 793 A (CHITRAPU PRABHAKAR ET AL) 18 February 1997 (1997-02-18) column 5, line 22 - line 33 claims	1
X	WO 95 22233 A (BESSETTE FRANCOIS ;NEWBRIDGE NETWORKS CORP (CA)) 17 August 1995 (1995-08-17)	7
A	page 3, line 13 -column 29	1-4,7-13
	--- -/--	

☒ Further documents are listed in the continuation of box C.

☒ Patent family members are listed in annex.

* Special categories of cited documents :

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"O" document referring to an oral disclosure, use, exhibition or other means

"P" document published prior to the international filing date but later than the priority date claimed

"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention

"X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone

"Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art.

"Z" document member of the same patent family

Date of the actual completion of the international search

15 June 2000

Date of mailing of the international search report

23/06/2000

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INTERNATIONAL SEARCH REPORT

International Application No
PCT/SE 99/02493

C.(Continuation) DOCUMENTS CONSIDERED TO BE RELEVANT

Category *	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	<p>RAMACHANDRAN RAMJEE ET AL: "ADAPTIVE PLAYOUT MECHANISMS FOR PACKETIZED AUDIO APPLICATIONS IN WIDE-AREA NETWORKS" PROCEEDINGS OF THE CONFERENCE ON COMPUTER COMMUNICATIONS (INFOCOM), TORONTO, JUNE 12 - 16, 1994, vol. 2, 12 June 1994 (1994-06-12), pages 680-688, XP000496524 INSTITUTE OF ELECTRICAL AND ELECTRONICS ENGINEERS paragraph '0002! paragraph '0003! : ----</p>	1-4,7-13
A	<p>MICHEL MOULY ET AL: "GSM - The System for Mobile Communications" GSM SYSTEM FOR MOBILE COMMUNICATIONS, COMPREHENSIVE OVERVIEW OF THE EUROPEAN DIGITAL CELLULAR SYSTEMS, 1992, pages 161-166, XP002106949 Communications Publishing, USA the whole document -----</p>	5,6,14, 15

INTERNATIONAL SEARCH REPORT

Information on patent family members

International Application No

PCT/SE 99/02493

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